

Sampling and Reconstruction

The sampling and reconstruction process

- Real world: continuous
- Digital world: discrete

Basic signal processing

- Fourier transforms
- The convolution theorem
- The sampling theorem

Aliasing and antialiasing

- Uniform supersampling
- Nonuniform supersampling

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Imagers = Signal Sampling

All imagers convert a continuous image to a discrete sampled image by integrating over the active "area" of a sensor.

$$R = \int_T \int_\Omega \int_A L(x, \omega, t) P(x) S(t) \cos \theta dA d\omega dt$$

Examples:

- Retina: photoreceptors
- CCD array

Virtual CG cameras do not integrate,
they simply sample radiance along rays ...

CS348B Lecture 8

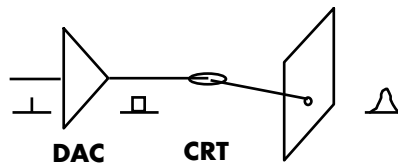
Pat Hanrahan, Spring 2004

Displays = Signal Reconstruction

All physical displays recreate a continuous image from a discrete sampled image by using a finite sized source of light for each pixel.

Examples:

- DACs: sample and hold
- Cathode ray tube: phosphor spot and grid



CS348B Lecture 8

Pat Hanrahan, Spring 2004

Sampling in Computer Graphics

Artifacts due to sampling - Aliasing

- Jaggies
- Moire
- Flickering small objects
- Sparkling highlights
- Temporal strobing

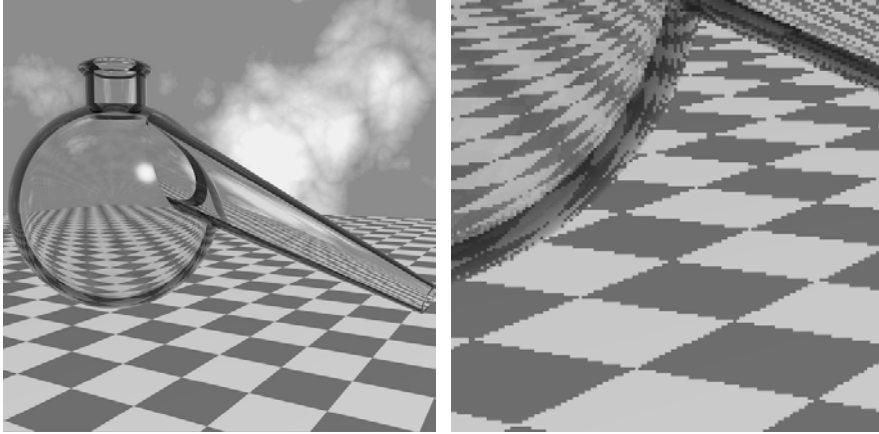
Preventing these artifacts - Antialiasing

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Jaggies

Retort sequence by Don Mitchell



Staircase pattern or jaggies

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Basic Signal Processing

Fourier Transforms

Spectral representation treats the function as a weighted sum of sines and cosines

Each function has two representations

- **Spatial domain - normal representation**
- **Frequency domain - spectral representation**

The *Fourier transform* converts between the spatial and frequency domain

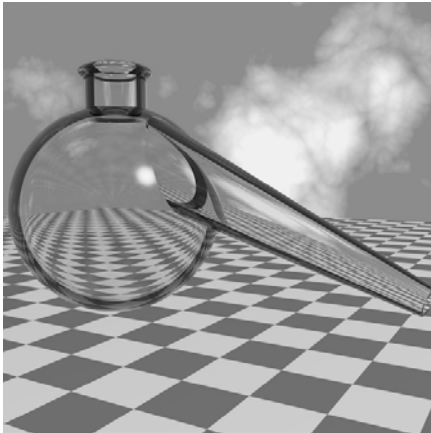
$$\begin{array}{ccc} \boxed{\text{Spatial Domain}} & \begin{array}{c} \Rightarrow F(\omega) = \int_{-\infty}^{\infty} f(x)e^{-i\omega x} dx \\ \Leftarrow f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega)e^{i\omega x} d\omega \Leftarrow \end{array} & \boxed{\text{Frequency Domain}} \end{array}$$

CS348B Lecture 8

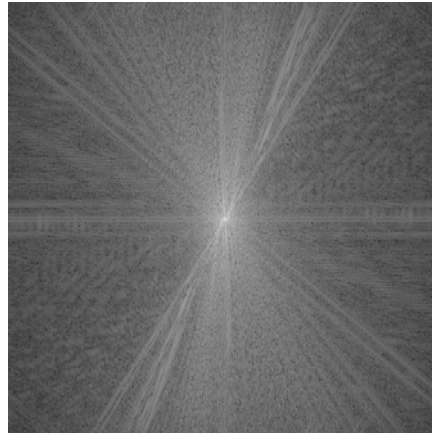
Pat Hanrahan, Spring 2004

Spatial and Frequency Domain

Spatial Domain



Frequency Domain



CS348B Lecture 8

Pat Hanrahan, Spring 2004

Convolution

Definition

$$h(x) = f \otimes g = \int f(x')g(x - x') dx'$$

Convolution Theorem: Multiplication in the frequency domain is equivalent to convolution in the space domain.

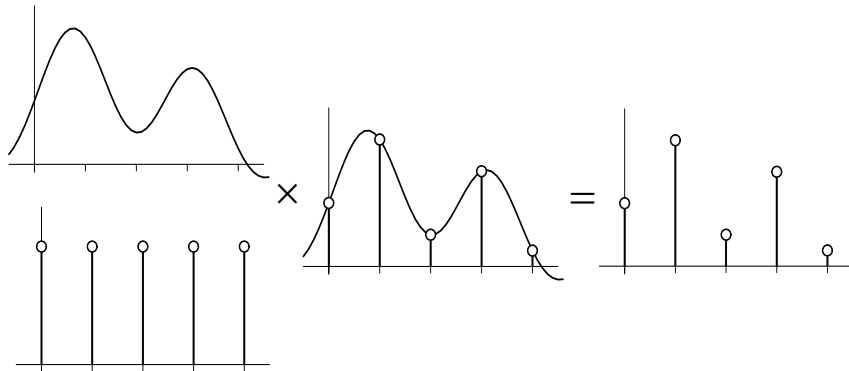
$$f \otimes g \leftrightarrow F \times G$$

Symmetric Theorem: Multiplication in the space domain is equivalent to convolution in the frequency domain.

$$f \times g \leftrightarrow F \otimes G$$

The Sampling Theorem

Sampling: Spatial Domain

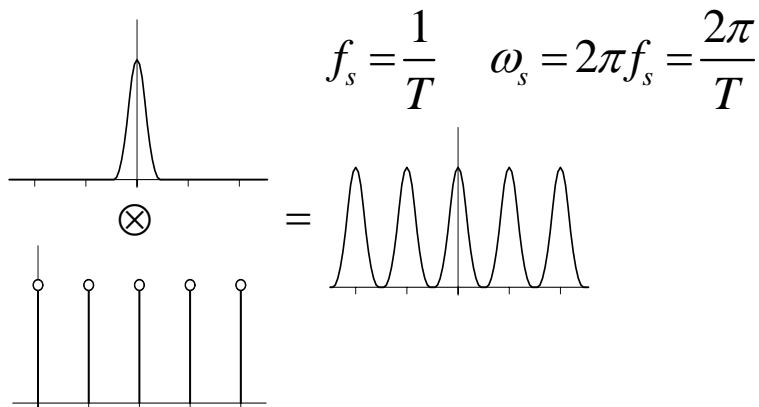


$$\text{III}(x) = \sum_{n=-\infty}^{n=\infty} \delta(x - nT)$$

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Sampling: Frequency Domain



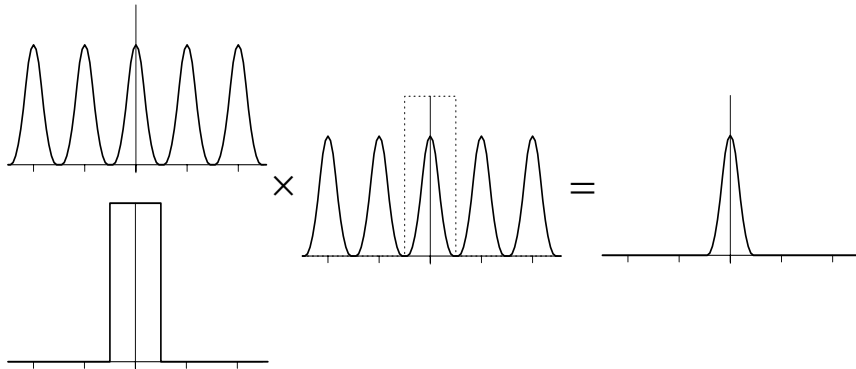
$$f_s = \frac{1}{T} \quad \omega_s = 2\pi f_s = \frac{2\pi}{T}$$

$$\text{III}(\omega) = \sum_{n=-\infty}^{n=\infty} \delta(\omega - n\omega_s)$$

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Reconstruction: Frequency Domain

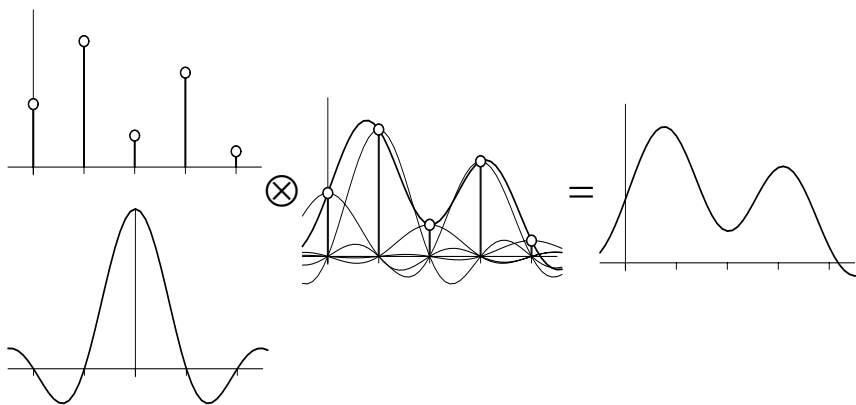


$$\Pi(x) = \begin{cases} 1 & |x| \leq \frac{1}{2} \\ 0 & |x| > \frac{1}{2} \end{cases}$$

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Reconstruction: Spatial Domain

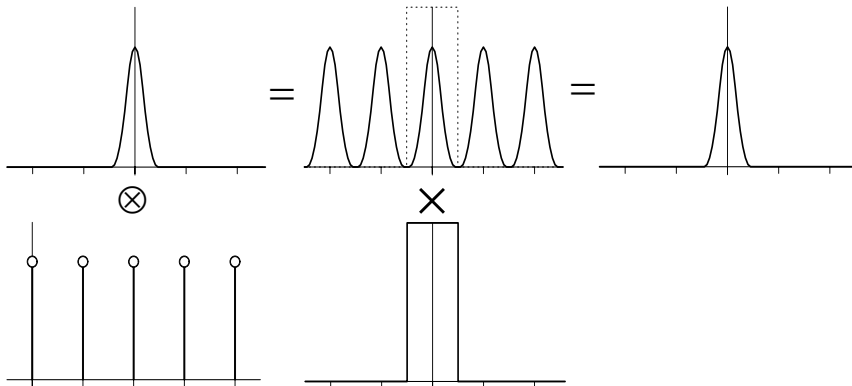


$$\text{sinc } x = \frac{\sin \pi x}{\pi x}$$

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Sampling and Reconstruction



CS348B Lecture 8

Pat Hanrahan, Spring 2004

Sampling Theorem

This result is known as the Sampling Theorem and is due to Claude Shannon who first discovered it in 1949

A signal can be reconstructed from its samples without loss of information, if the original signal has no frequencies above 1/2 the Sampling frequency

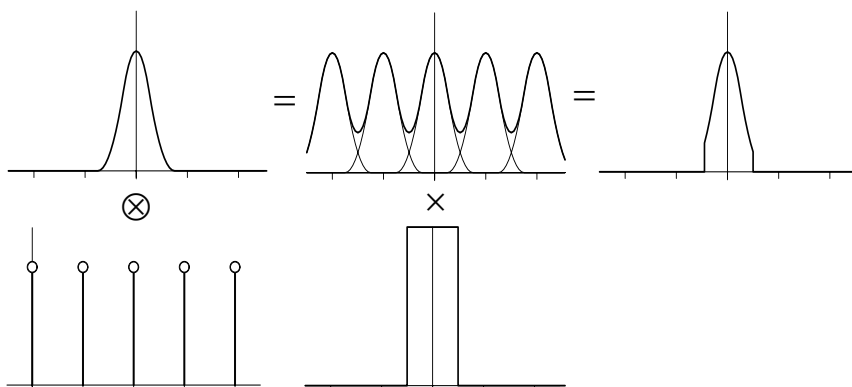
For a given bandlimited function, the rate at which it must be sampled is called the *Nyquist Frequency*

CS348B Lecture 8

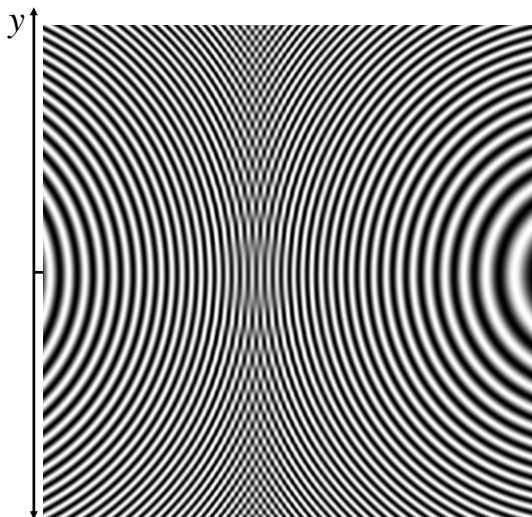
Pat Hanrahan, Spring 2004

Aliasing

Undersampling: Aliasing



Sampling a "Zone Plate"



Zone plate: $\sin x^2 + y^2$

**Sampled at 128x128
Reconstructed to 512x512
Using a 30-wide
Kaiser windowed sinc**

**Left rings: part of signal
Right rings: prealiasing**

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Ideal Reconstruction

Ideally, use a perfect low-pass filter - the sinc function - to bandlimit the sampled signal and thus remove all copies of the spectra introduced by sampling

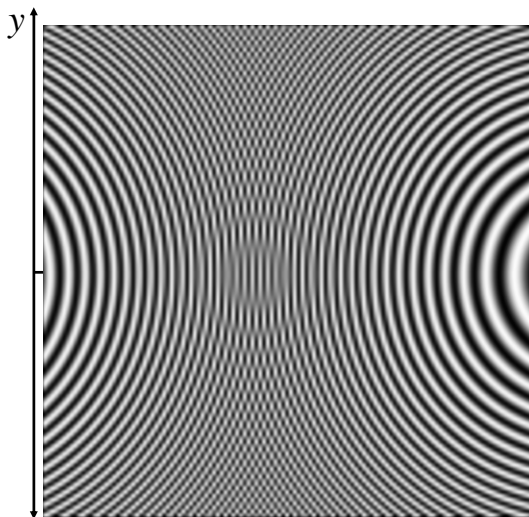
Unfortunately,

- **The sinc has infinite extent and we must use simpler filters with finite extents. Physical processes in particular do not reconstruct with sincs**
- **The sinc may introduce ringing which are perceptually objectionable**

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Sampling a "Zone Plate"



Zone plate: $\sin x^2 + y^2$

**Sampled at 128x128
Reconstructed to 512x512
Using optimal cubic**

**Left rings: part of signal
Right rings: prealiasing
Middle rings: postaliasing**

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Mitchell Cubic Filter

$$h(x) = \frac{1}{6} \begin{cases} (12 - 9B - 6C)x^3 + (-18 + 12B + 6C)x^2 + (6 - 2B) & |x| < 1 \\ (-B - 6C)x^3 + (6B + 30C)x^2 + (-12B - 48C)x + (8B + 24C) & 1 < |x| < 2 \\ 0 & \text{otherwise} \end{cases}$$

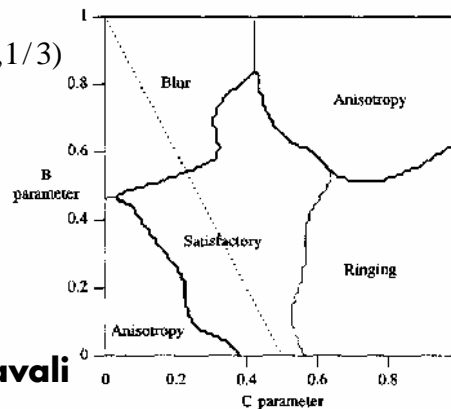
Properties:

$$\sum_{n=-\infty}^{\infty} h(x) = 1$$

B-spline: (1, 0)

Catmull-Rom: (0, 1/2)

Good: (1/3, 1/3)



From Mitchell and Netravali

CS348B Lecture 8

Pat Hanrahan, Spring 2004

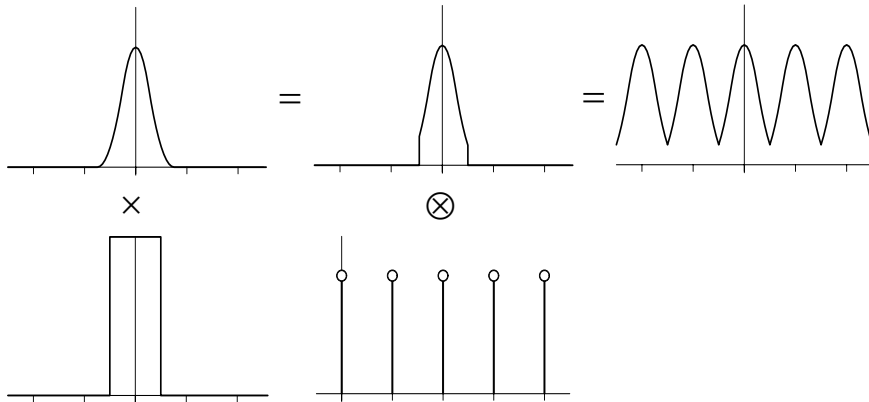
Antialiasing

Antialiasing

Antialiasing = Preventing aliasing

- 1. Analytically prefilter the signal**
 - Solvable for points, lines and polygons
 - Not solvable in general
e.g. procedurally defined images
- 2. Uniform supersampling and resample**
- 3. Nonuniform or stochastic sampling**

Antialiasing by Prefiltering



Frequency Space

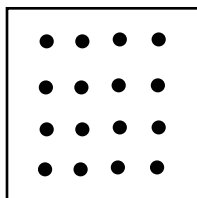
CS348B Lecture 8

Pat Hanrahan, Spring 2004

Uniform Supersampling

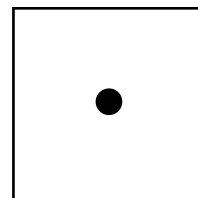
Increasing the sampling rate moves each copy of the spectra further apart, potentially reducing the overlap and thus aliasing

Resulting samples must be resampled (filtered) to image sampling rate



Samples

$$Pixel = \sum_s w_s \cdot Sample_s$$

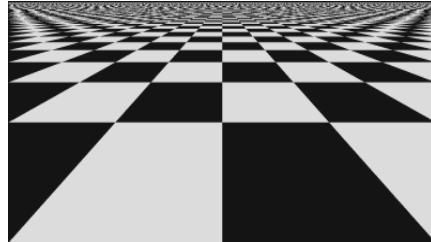
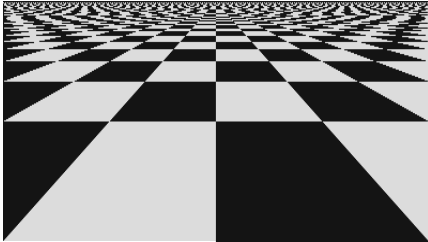
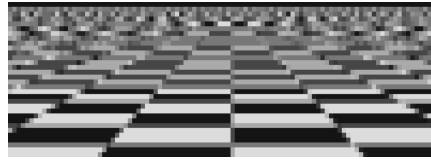
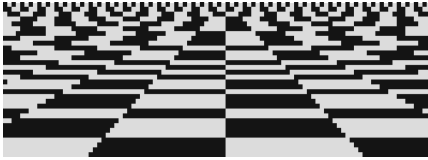


Pixel

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Point vs. Supersampled



Point

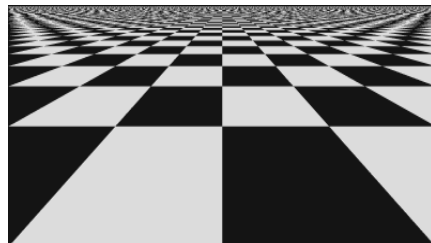
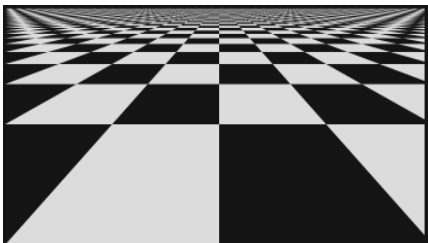
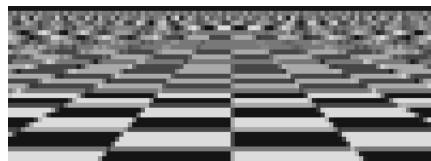
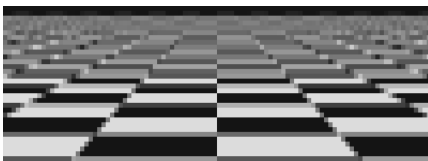
4x4 Supersampled

Checkerboard sequence by Tom Duff

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Analytic vs. Supersampled



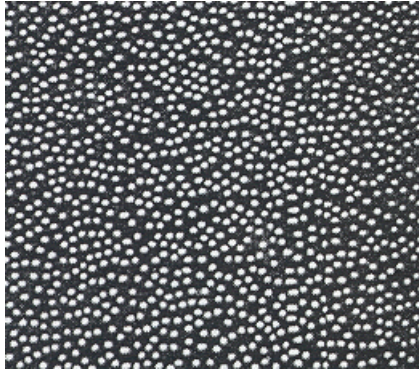
Exact Area

4x4 Supersampled

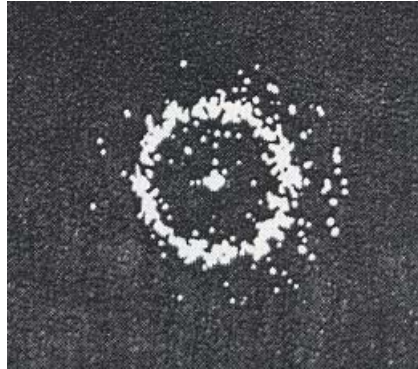
CS348B Lecture 8

Pat Hanrahan, Spring 2004

Distribution of Extrafoveal Cones



Monkey eye
cone distribution



Fourier transform

Yellot theory

- Aliases replaced by noise
- Visual system less sensitive to high freq noise

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Non-uniform Sampling

Intuition

Uniform sampling

- The spectrum of uniformly spaced samples is also a set of uniformly spaced spikes
- Multiplying the signal by the sampling pattern corresponds to placing a copy of the spectrum at each spike (in freq. space)
- Aliases are coherent, and very noticeable

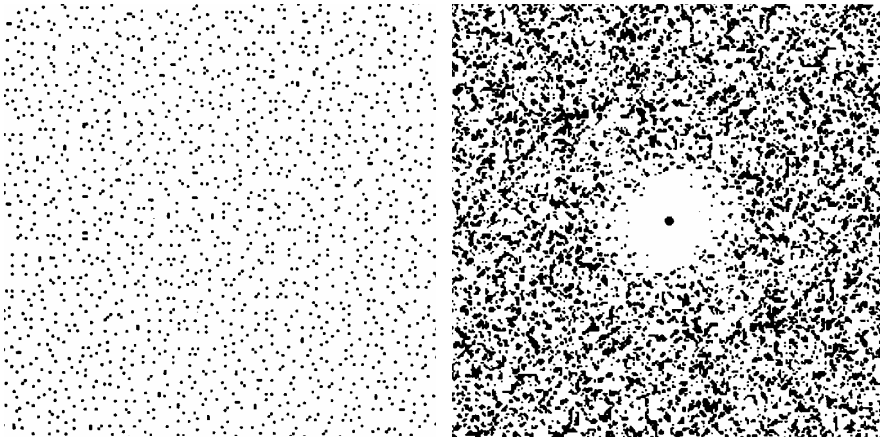
Non-uniform sampling

- Samples at non-uniform locations have a different spectrum; a single spike plus noise
- Sampling a signal in this way converts aliases into broadband noise
- Noise is incoherent, and much less objectionable

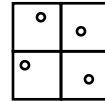
CS348B Lecture 8

Pat Hanrahan, Spring 2004

Jittered Sampling



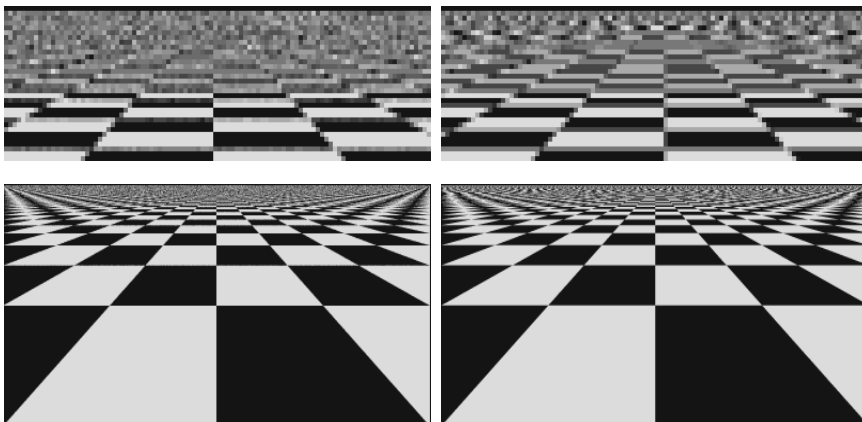
Add uniform random jitter to each sample



CS348B Lecture 8

Pat Hanrahan, Spring 2004

Jittered vs. Uniform Supersampling



4x4 Jittered Sampling

4x4 Uniform

CS348B Lecture 8

Pat Hanrahan, Spring 2004

Analysis of Jitter

Non-uniform sampling

$$s(x) = \sum_{n=-\infty}^{n=\infty} \delta(x - x_n)$$

$$x_n = nT + j_n$$

Jittered sampling

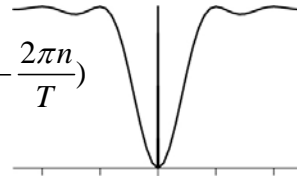
$$j_n \sim j(x)$$

$$j(x) = \begin{cases} 1 & |x| \leq 1/2 \\ 0 & |x| > 1/2 \end{cases}$$

$$J(\omega) = \text{sinc } \omega$$

$$S(\omega) = \frac{1}{T} \left[1 - |J(\omega)|^2 \right] + \frac{2\pi}{T^2} |J(\omega)|^2 \sum_{n=-\infty}^{n=\infty} \delta\left(\omega - \frac{2\pi n}{T}\right)$$

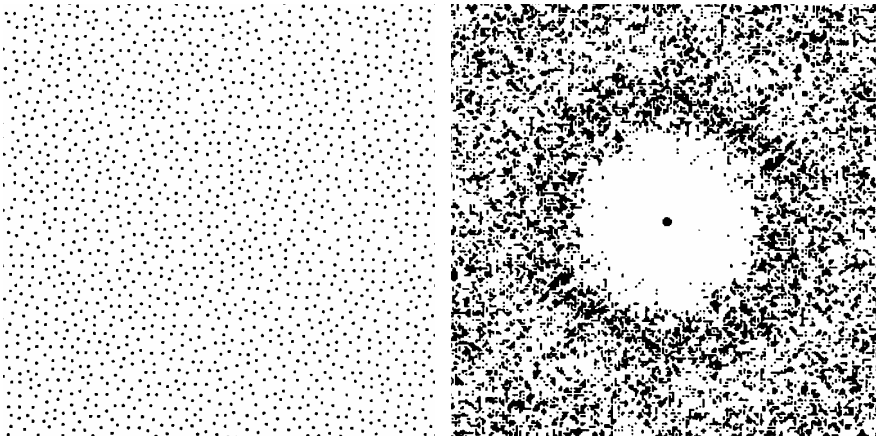
$$= \frac{1}{T} \left[1 - \text{sinc}^2 \omega \right] + \delta(\omega)$$



CS348B Lecture 8

Pat Hanrahan, Spring 2004

Poisson Disk Sampling



Dart throwing algorithm

CS348B Lecture 8

Pat Hanrahan, Spring 2004